Α	n unconventional adaptation of a classical Gaussian plume dispersion scheme for the fast assessment of external irradiation from a radioactive cloud
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Abstract

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This article focuses on derivation of an effective algorithm for the fast estimation of cloudshine doses/dose rates induced by a large mixture of radionuclides discharged into the atmosphere. A certain special modification of the classical Gaussian plume approach is proposed for approximation of the near-field dispersion problem. Specifically, the accidental radioactivity release is subdivided into consecutive one-hour Gaussian segments, each driven by a shortterm meteorological forecast for the respective hours. Determination of the physical quantity of photon fluence rate from an ambient cloud irradiation is coupled to a special decomposition of the Gaussian plume shape into the equivalent virtual elliptic disks. It facilitates solution of the formerly used time-consuming 3-D integration and provides advantages with regard to acceleration of the computational process on a local scale. An optimal choice of integration limit is adopted on the basis of the mean free path of p-photons in the air. An efficient approach is introduced for treatment of a wide range of energetic spectrum of the emitted photons when the usual multi-nuclide approach is replaced by a new multi-group scheme. The algorithm is capable of generating the radiological responses in a large net of spatial nodes. It predetermines the proposed procedure such as a proper tool for online data assimilation analysis in the nearfield areas. A specific technique for numerical integration is verified on the basis of comparison with a partial analytical solution. Convergence of the finite cloud approximation to the tabulated semi-infinite cloud values for dose conversion factors was validated.

Keywords: Photon fluence, atmospheric dispersion, cloudshine dose

35 1. Introduction

The main goal of this article is to formulate a fast and sufficiently accurate approach for estimation of 37 the cloudshine irradiation doses which replaces the former rough estimations. The shape of a 38 radioactive plume in the atmosphere near the source of pollution is narrow (especially for a stable 39 atmospheric stratification like category F) and does not noticeably diffuse to the surface until it has 40 travelled a distance of several kilometres from the point of discharge (even more than 10 km for a 41 buoyant plume). Due to the buoyant and vertical momentum plume rise the effective height can 42 markedly increase. The vertical concentration profile is gradually getting homogenous only from 43 greater distances. Common practice introduces the calculation of the ground-level cloudshine dose 44 rates at larger distances as a product of this homogenised near-ground activity concentration and the 45 tabulated conversion coefficient R_{cloud} (Sv.m³.Bq⁻¹.s⁻¹) defined in (ICRP 74, 1996). The technique of 46 the irradiation calculations is designated as a semi-infinite cloud approach. Its application at near 47 distances can, however, cause huge errors and the real finite plume shape should be respected. Further 48 development led to the time-consuming calculations based on a three-dimensional integration over the 49 finite cloud volume (e.g. ADMS4, 2009, Overcamp, 2007) or on a specially partitioned integration 50 space (Wang et al., 2004, Raza et al., 2001). The 3-D integration of the Gaussian plume is fairly 51 complex and computationally expensive, and in many cases sufficiently accurate approximations 52

could be constructed. The volume integral for gamma doses was formerly approximated by using the 53 semi-infinite cloud model combined with correction factors. The first attempt to solve the problem 54 was the former approach based on introduction of a certain tabulated finite cloud correction factors 55 F^{cor} (Slade, 1968). The similar approach based on a pre-calculated matrix of the cloud gamma 56 correction factors was used in (ATSTEP, 2000) - parameterisation in the photon energy, horizontal 57 dispersion coefficient, roughness length, plume height, and stability class. An analogical procedure is 58 used in (Thykier-Nielsen et al., 1995) in the Lagrangian puff model RIMPUFF for the calculation of 59 gamma doses from assymetrical puffs. The multi-parameter gamma dose values are pre-calculated as a 60 function of the photon energy, horizontal dispersion and asymmetry factor, height of puff centre and 61 62 the distance from the puff base point. We have two main objections to the pre-calculated procedures. Firstly, due to the steep gradients of activity concentration a suitable interpolation on the fixed spatial 63 grid could be problematic. Secondly, we have to include possible elevated locations of the receptors 64 (e.g. real orography of the terrain, monitoring towers). Our proposed method inherently solves the 3-D 65 configuration of the receptors, which can be crucial for the determination of a dangerous flight levels 66 for an aircrew during the aerial monitoring. 67 68 An ultimate aim of our research is improvement of the model predictions of this radiological situation based on assimilation with real observations incoming from the terrain. The assimilation procedures 69

perform statistical merging of the model predictions and the measured values in the observation space.
 Its dimension equals the number of monitoring sensors on the terrain and, therefore, a parallel

Its dimension equals the number of monitoring sensors on the terrain and, therefore, a parallel simulation of the dose rate responses on a large net of receptors in the terrain from a wide group of

12 simulation of the dose rate responses on a rarge net of receptors in the terrain from a wide group of 13 leaking radionuclides is essential. At the same time some special online examinations like predicting

the time to the first alarm or investigating the weakest plume detectability can be accomplished. From

a general point of view the fast and effective method for estimation of the finite cloud problem at near

76 distances facilitates the realisation of the assimilation techniques. Advanced assimilation techniques

coming from sequential Monte-Carlo methods are computationally expensive (e.g. Doucet *et al.*,

2001) and an effective procedure for fast simulation of external irradiation has a crucial significance

79 (ASIM, 2012). Our first attempts at Bayesian tracking began in (Pecha *et al.* 2009). The recent

application of inverse modelling techniques for extracting of the model parameter information from the incoming terrain observations is described in (Smidl *et al.* 2013).

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84 **2. Predictions of harmful admixture propagation nearby a source**

This article deals with adaptation of the classical solution of a diffusion equation in the initial phase of 86 radioactive plume drifting. The analysis should satisfactorily cover the area of a teledosimetric ring of 87 sensors (TDS) located within a few hundred metres around a source. The 3-D distribution of the 88 specific radioactivity concentration C^n of nuclide *n* in the air $(Bq.m^{-3})$ is expressed by the straight-line 89 Gaussian solution. This near-field model has a long tradition of use for dispersion predictions. Even 90 though it is simple, the Gaussian model is consistent with the random nature of turbulence (Hanna et 91 al., 1982). It is a solution of the Fickian diffusion equation for constant diffusivity coefficient K and 92 average plume velocity \overline{u} . The model is tuned to experimental data and offers quicker estimation with 93 a reasonable computational effort. Proved semi-empirical formulae are available for approximation of 94 important effects such as interaction of the plume with near-standing buildings or momentum and 95 buoyant *plume rise* during release. Semi-empirical formulae are introduced for estimation of the wind 96 speed changes with height and for depletion of the plume radioactivity due to the removal processes of 97 dry and wet deposition and radioactive decay. Separate transport mechanisms of radioactivity 98 according to the physical-chemical forms of admixtures and landuse characteristics are considered. 99 100 The effects of small changes of *surface elevation* and *terrain roughness* on atmospheric dispersion can be approximately included. 101

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Figure 1. The finite cloud propagation during stepwise changes of meteorological conditions. Weather changes observed/forecast for the point of release for a particular time step ΔT^{segm} are assumed to immediately impact the propagation of all previous segments in their corresponding phases.

Let assume the continuous radioactivity release to be decomposed into consecutive time segments 109 s. The straight-line Gaussian solution is taken for description of each segment s in its first time step 110 ΔT^{segm} of propagation within the time interval $\langle 0; \Delta T^{segm} \rangle$. In the subsequent time phases f of the 111 segment s the meteorological conditions have to be considered more realistically. For this purposes a 112 segmented Gaussian plume model (SGPM) is introduced (Hofman and Pecha, 2011). The model 113 together with the algorithm proposed here is fully integrated into the environmental code HARP 114 (HAzardous Radioactivity Propagation). The model SGPM is initiated from the first phase f=1 of the 115 straight-line propagation supposing the longitudinal dispersion is neglected. The analytical shape of 116 the partial plume confined on interval $x \in \langle 0; \Delta T^{segm}, \overline{u} \rangle$ is described by expression (1). In the 117 consecutive phases f > I the segment s is drifted according to the current changes of meteorological 118 conditions. The further dispersion and deposition (e.g. $(s=1;f=1) \rightarrow (s=1;f=2)$ in Figure 1) is 119 simulated using the SGPM algorithm by means of a large number of elemental shifts driven by the 120 new weather conditions (HARP, 2011). During each shift the activity depletion in the cloud due to dry 121 122 and wet deposition and radioactivity decay is assumed. A complicated scenario of a release time progress is synchronized with the available meteorological observations/forecasts. 123

The plume is assumed to be driven through the near vicinity by weather forecast given for the point 124 of release. The time step of extents ΔT^{segm} should be selected according to accessibility of the 125 meteorological data (one-hour or half an hour). During each time interval ΔT^{segm} a new set of the local 126 observed/forecast meteorological data is assumed to be available in the nearest vicinity of the source. 127 128 We can hardly expect to have the weather data in a fine spatial and time resolution (let us say for a few hundred meters from the source). We have adopted a certain intuitive subjective assumption for the 129 plume spread in the nearest vicinity according to the sketch shown in Figure 1. In this case the weather 130 changes observed/forecast for the point of release for a particular time step ΔT^{segm} immediately and in 131 the same way impact the propagation of all segments in their corresponding phases. The interval 132 133 ΔT^{segm} of on-site meteorological measurements is typically from several minutes to one hour. Besides information related to the source of release we are also using a short-term meteorological forecast: 48 134 hours forward on the spatial grid on an area of 200×200 km around the source of pollution. It enables 135 us to connect the plume tracing at larger distances with the previous nearest-range analysis. 136 The initial straight-line plume propagation during the time step extent ΔT^{segm} is simulated by

The initial straight-line plume propagation during the time step extent ΔT^{eegm} is simulated simplified solution of the diffusion equation in the form:

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$$C^{n}(x, y, z) = \frac{A^{n}}{2\pi \cdot \sigma_{y}(x) \cdot \sigma_{z}(x) \cdot \overline{u}} \cdot \exp(-\frac{y^{2}}{2\sigma_{y}^{2}(x)}) \cdot \left[\exp(-\frac{(z - h_{ef})^{2}}{2\sigma_{z}^{2}(x)}) + \exp(-\frac{(z + h_{ef})^{2}}{2\sigma_{z}^{2}(x)}) + (1)\right]$$

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$$+\exp(-\frac{(z-2H_{mix}+h_{ef})^2}{2\sigma_z^2(x)})+\eta_{JV}(x,z)$$
 $\cdot f_R^{\ n}(x)\cdot f_F^{\ n}(x)\cdot f_W^{\ n}(x)$

141	$C^n(x,y,z)$	Specific activity of radionuclide <i>n</i> in spatial point (x, y, z) in $(Bq.m^{-3})$;
142		x – direction of spreading; y , z – horizontal and vertical coordinates
143	$\sigma_{y}(x), \sigma_{z}(x)$	Horizontal and vertical dispersion coefficients at distance x from the source (m);
144		expressed by empirical formulae
145	A^n	Continuous release source strength of nuclide n ($Bq.s^{-1}$); continuous and constant
146		within the time interval ΔT^{segm}
147	\overline{u}	Mean advection velocity of the plume in direction $x (m.s^{-1})$
148	$h_{\it ef}$, $H_{\it mix}$	Effective height of the plume axis over the terrain (m) , height of planetary mixing
149		layer (m)
150	$\eta_{JV}(x,z)$	Effect of additional multiple reflections on ground and inversion layer/mixing height
151		(for this near-field model hereafter ignored)
152	f^n_R, f^n_F, f^n_W	Plume depletion factors due to radioactive decay and dry and wet deposition. The
153		latter two are dependent on the physical-chemical form (aerosol, organic, elemental)
154		of nuclide <i>n</i> . The factors stand for the "source depletion" approach introduced into the
155		classical straight-line Gaussian solution. The release source strength at distance x is
156		depleted according to $A^n(x, y=0, z=h_{ef}) = A^n(x=0, y=0, z=h_{ef}) \cdot f^n_{R}(x) \cdot f^n_{F}(x) \cdot f^n_{W}(x)$
157		more in (HARP, 2011).
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The exponential terms in equation (1) from left to right mean the basic diffusion growth of the 159 plume, its reflection in the ground plane and its reflection from the top of mixing layer H_{mix} . The 160 designed atmospheric dispersion model SGPM was compared with international codes COSYMA and 161 RODOS (Pecha and Pechova, 2002; HARP, 2011). The documentation of the HARP system and other 162 additional comparisons are described in detail in (HARP, 2011). The applicability of the straight-line 163 propagation in the first hour of a release is limited on the near field areas inside the emergency 164 planning zone around a nuclear facility up to 15 - 20 kilometres. For a simple scenario the results are 165 well comparable with the time consuming techniques based on Lagrangian particle dispersion models 166 (e. g. NAME III (Bedwell et al., 2010); Armand et al., 2005)) - see Section 6. 167

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3. Proposition of the fast scheme for evaluation of external irradiation from radioactive cloud 170

171 We shall consider the physical quantity of the photon fluence which represents a number of monoenergetic γ photons with energy E_{γ} passing through a specific area. Transport of photons with 172 energy E_{γ} from the source of emission to the receptors R will be described by the quantity of photon 173 fluence rate $\Phi(E_{\gamma}, \mathbf{R})$ in units $(m^{-2} \cdot s^{-1})$. External exposure from the finite plume can be estimated 174 when applying traditional methods based on three-dimensional integration over the cloud (e.g. 175 ADMS4, 2009) or on specially constructed three-dimensional columned space divided into many 176 finite grid cells (e.g. Wang et al., 2004). Photon fluence rate at a receptor point R on the terrain from 177 the whole plume volume V_{plume} emitting monoenergetic γ -photons of energy E_{γ} is calculated 178 according to the three-dimensional integration given by equation (2). 179

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$$\Phi_{total}(E_{\gamma}, R) = \iiint_{V_{plame}} \frac{f^{n}(E_{\gamma}) \cdot C^{n}(x, y, z) \cdot B(E_{\gamma}, \mu(E_{\gamma}) \cdot d) \cdot \exp(-\mu(E_{\gamma}) \cdot d)}{4\pi d^{2}} dV$$
(2)

181 where $\mu(E_{\gamma})$ is the linear attenuation factor (m^{-1}) , *d* denotes the distance between the receptor point R 182 and the plume elemental volume dV. $B(E_{\gamma}, \mu(E_{\gamma}) \cdot d)$ stands for the build-up factor. We use its linear

183 form $B(E_{\gamma}, \mu \cdot d) = 1 + k \cdot \mu \cdot d$. Here $k = (\mu - \mu_a)/\mu_a$, μ_a stands for the linear energy absorption coefficient

(m⁻¹). Both coefficients are related to the monoenergetic photons with energy E_{γ} . Comparison of the linear form with the alternative Berger's formula can be found in literature, e.g. in (Overcamp, 2007). Specifically, we can assume the monoenergetic γ -photons emitted by the radionuclide *n*. The value $f^{n}(E_{\gamma})$ is the branching ratio for radionuclide *n* to the specified energy E_{γ} . Activity concentration C^{n} of radionuclide *n* in the air is given by the analytic equation (1).

189 Continuous and constant release in direction of axis *x* with average velocity \overline{u} is partitioned into an 190 equivalent number of elliptic discs according to Figure 2. The thickness of the discs Δx was tested for 191 the optimal choice (see conclusion in Table 1 below). The centre of the disc *i* reaches the position $x_i =$

 $(i-1/2) \times \Delta x$ in x_i / \overline{u} seconds. A discrete technique is introduced when the model parameters are

- averaged within interval Δx on the disc *i*. Distribution of the activity concentration in the disc *i* on the
- 194 plane $x = x_i$ (it means the average value on Δx) is driven according to the straight-line equation (1)
- where the corresponding averaged disc parameters are inserted (e.g. x_i , $\sigma_y(x_i)$, $\sigma_z(x_i)$, depletion

196 factors $f_R^n(x_i) \cdot f_F^n(x_i) \cdot f_W^n(x_i)$ etc.).

The $5/\mu(E_{\gamma})$ method (Wang et al., 2004) (generally $m/\mu(E_{\gamma})$ method – the values m=5,10,15 were 197 tested) imposes an integration limit up to d_{max} and indicates as significant only those sources of 198 irradiation that lie within a distance of $5/\mu(E_{\gamma})$ from the receptor R. The integration boundary (see also 199 the integration circle in Figure 3) is formed by intersection of the cone (receptor R is in the cone 200 vertex) and the plane of the newest disc I. Only the points located inside are assumed to contribute to 201 the fluence rate at R. This markedly accelerates the computational speed and improves the capability 202 203 of the assimilation procedures to run successfully in real time mode. It can, for a near-field problem, serve as an effective alternative to computationally expensive traditional methods based on full 3-D 204

205 integration techniques (Raza *et al.*, 2001).





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Figure 2. Partitioning of continuous Gaussian shape into equivalent elliptical disc sequence i (i=1,...,I). Irradiation of receptor R from the last disc I is illustrated.

A substantial performance improvement makes the $5/\mu(E_{\gamma})$ approach the first choice for its application during nuclear emergency situations (Wang *et al.*, 2004). Minor differences from the traditional methods of coarse 3-D integration are referred to here for a broad range of input model parameters (stability classes, axial distances, source term characteristics etc.). The partial results of spatial progression for stability classes F and D are given in Figure 5 below. A comparison benchmark of the results with several European codes is presented in Section 6.2.

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4. Replacement of traditional 3-D integration by stepwise 2-D computational scheme

218 4.1 Formulation of the stepwise 2-D computational approach

- External irradiation from the plume section on interval $\langle x_i \Delta x/2; x_i + \Delta x/2 \rangle$ is substituted by an
- equivalent effect of a disc of thickness Δx with averaged model parameters on $\langle x_i \Delta x/2; x_i + \Delta x/2 \rangle$.
- 221 Let us analyse the contribution to the fluence rate at the receptor R from irradiation with

- monoenergetic photons having energy E_{γ} from the elliptical disc *I*. A lateral view of the partitioned
- 223 plume propagation is demonstrated in Figure 2. The same situation is outlined in the front view in
- Figure 3. The boundary of the integration region lying in the plane of disc *I* is based on
- 225 $5/\mu(E_{\gamma})$ approximation (bold dashed line composed of the part of the circle above ground with a radius 226 of r_{max} and with its centre in the point Q). For r_{max} the relationship $r_{max}^2 = (5/\mu(E_{\gamma}))^2 - [x(R) - x(Q)]^2$ 227 holds true. The points S and Q are lying in the plane of disc I (S is its centre, the abscissa RQ is
- 228 perpendicular to the plane). Contribution of the disc *I* with unit thickness $\Delta x=1$ m to the photon 229 fluence rate at receptor R is given by:
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$$\Phi^{\Delta x=1}\left(E_{\gamma}, R, I, x_{I}\right) = \frac{1}{4\pi} \int_{r=0}^{r_{\text{max}}} \int_{\varphi=0}^{2\pi} \frac{f^{n}(E_{\gamma})C^{I}\left(x_{I}; r, \varphi\right) \cdot B\left(E_{\gamma}, \mu(E_{\gamma}) \cdot d\right) \cdot \exp\left(-\mu(E_{\gamma}) \cdot d\right)}{d^{2}} r \, d\varphi \, dr$$
232 (3a)

233 The contribution from the disc *I*, which in general has a thickness of Δx , can be roughly expressed as:

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$$\Phi(E_{\gamma}, R, I) = \Delta x \cdot \Phi^{\Delta x = 1}(E_{\gamma}, R, I, x_{I})$$
(3b)

Referring to Figure 3, the value of d is distance between points R(x(R), y(R), z(R)) and M(x(S), y(M), z(R))

- 236 $z(\mathbf{M})$; $d^2 = (x(\mathbf{S}) x(\mathbf{R}))^2 + (y(\mathbf{M}) y(\mathbf{R}))^2 + (z(\mathbf{M}) z(\mathbf{R}))^2$; $x(\mathbf{S}) = x_I = (I 1/2) \times \Delta x$ is the distance of
- 237 the centre of the disc *I* from the release point; $y(M) = y(R) + r \times sin(\varphi)$; $z(M) = z(R) + r \times cos(\varphi)$. The
- equivalent specific source strength $C^{I}(x_{I}, y, z)$ of emitted monoenergetic photons in the disc *I* is
- expressed using C^n from equation (1) multiplied by branching ratio $f^n(E_{\gamma})$. Valid values of coordinate z
- should be positive, dispersion coefficients and depletion factors are calculated for position x_I (it means

for a time of x_{I}/\bar{u} seconds) and are dependent on the physical-chemical form of the respective

radionuclide.



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Figure 3. (Coupled with Figure 2): Frontal view from the receptor point R to the elliptical disc *I* and circular integration region (bold dashed line).

An equivalent source strength for the disc *I* includes source depletion model and substitutes the original discharge from equation (1) according to $A(x_b, y=0, z=h_{ef}) = A(x=0, y=0, z=h_{ef}) \cdot f_R(x_I) \cdot f_F$ (x_I) $\cdot f_W(x_I)$. During computation the values of photon fluence rates are gradually stored into the array $F(1:N_{sens}, 1:I_{total})$. Here N_{sens} means the number of receptors being simultaneously taken into account, and I_{total} stands for the total number of discs with thickness Δx of the plume separation (I_{total} is in order of 10^3). The total fluence rates, total fluencies and the corresponding total cloudshine doses/dose rates are generated by processing of the array values in the particular time steps x_i/\overline{u} , $i=1, ..., I_{total}$.

4.2. Selecting the computational grid size in practice

The proposed stepwise numerical scheme is shown in Figure 2. The precision of calculations on the one hand and computational time on the other hand depend on the choice of the disc thickness Δx

258 entering the equation (3). Thickness of the discs was tested for selected values $\Delta x = 1$ m, 10m, 50m (see the conclusions in Table 1 below). Table 1 demonstrates the importance of an effective choice of 259 the thickness value Δx . Fine resolution $\Delta x=1$ m leads to about 50 times prolongation of the calculations 260 with respect to the rough grid $\Delta x=50$ m. The latter one gives some differences, mainly at locations 261 near the source of pollution. Practically all computations were performed with $\Delta x = 10$ m proposed 262 here as an optimum compromise between the precision and speed of computation. The affirmation 263 should be valid for all nuclides (¹³³Xe has almost the lowest $\overline{E}^{Xe_{133}}$ (see Table 4) and does have the 264 lowest mean free path in air). 265

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267**Table 1.** Photon fluence rate induced by a plume as a function of Δx from equation (3b). Responses on sensors268TST01 and TST02 just T_{minute} after the start of continuous release of ¹³³Xe with source strength from Table 4.269Duration of release is 1 hour.

		Photon fluence rate $(m^{-2} \cdot s^{-1})^{a}$			
Sensor	$T_{minute}(\min)$	$\Delta x=1 \mathrm{m}$	$\Delta x=10m$	$\Delta x=50$ m	
TST01	5	1.568 E+11	1.452 E+11	8.180 E+10	
TST01	6	4.745 E+11	4.786 E+11	4.727 E+11	
TST01	$\geq 8^{c}$	5.485 E+11	5.483 E+11	5.373 E+11	
TST02	20	1.101 E+11	1.035 E+11	1.259 E+11	
TST02	$\geq 23^{\circ}$	2.813 E+11	2.760 E+11	2.469 E+11	
Relative time of 1 hour of the cl	computation up to oud propagation	1.0	~0.10	~0.02	

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272 273 ^a continuous release of radionuclide ¹³³Xe with the source strength 2.28 E+14 Bq s⁻¹

^b TST01, TST02 are located at 400 m and 1500 m respectively from the source

^c equilibrium values of photon fluence rate are constant up to the end of the continuous release

However, the equilibrium values can apparently be generated even with rough grid sizes. The values of the photon fluence rates at certain positions can reach their equilibrium values during a long-lasting release and remain constant for the remaining progress of the plume (e.g. see constant part of the courses in Figure 4 left).

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Formulation of the fast computational procedure in the initial phase of the plume propagation

282 The subsequent post-processing of the array F described above provides a sufficient approximation to 283 the basic solution described by equation (3). Figure 2 shows the scheme for the fragmentation of the 284 plume shape into the consecutive virtual elliptical discs. The first segment of propagation during the 285 time steps ΔT^{segm} is assumed to be described by the corresponding part of straight-line Gaussian 286 formula. In the following text we shall examine a basic task, namely a linear drifting of the segment in 287 its first phase f=1 (described in Figures 1 and 2) and generation of responses in a large net of sensors. 288 The analysis for the first phase f=1 is of essential significance because it comprises the teledosimetric 289 ring of sensors (TDS) on the fence of the nuclear power plant (roughly 25 sensors at distances of 290 approximately 500 meters from the hypothetical source of pollution). The ring plays the decisive role 291 in re-estimation of the source term of release and some other model parameters on the basis of 292 293 assimilation with incoming terrain measurements.

The front of the plume is determined by the position of the latest disc *I* of the bundle of discs which corresponds to the time of spreading $t_I = I \times \Delta x / \overline{u}$. Recurrent formulae for processing an array of fluencies can be derived when distinguishing between two situations.

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5.1. The continuous release with steady state discharge rate of admixtures persists

Let us assume the front of the plume has reached the position of the disc I, and propagation to the I+1300 disc is in progress. Contribution of each elemental disc i=1, ..., I to the fluence rate $\Phi(E_v, \mathbf{R}, i)$ at 301 receptor R was calculated in the previous steps and stored in the array F. The new contribution $\Phi(E_n)$ 302 R, I+1) of the disc I+1 is calculated using integration (3). The recurrent formula for overall fluence 303 rate at receptor *R* can be formally rewritten as: 304

$$\Phi\left(E_{\gamma}, R, i=1, \dots, I+1\right) = \Phi\left(E_{\gamma}, R, i=1, \dots, I\right) + \Phi\left(E_{\gamma}, R, I+1\right)$$

$$where \qquad \Phi\left(E_{\gamma}, R, i=1, \dots, I\right) = \sum_{i=1}^{i=I} \Phi\left(E_{\gamma}, R, i\right)$$
(4)

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Then, the only computation effort is to evaluate 2-D integration of the latest disc I+I. Analogously, 306 the recurrent formula for the entire photon fluence at receptor R from the same beginning of the 307 release is given by: 308

$$\Psi(E_{\gamma}, R, i = 1, \dots, I+1) = \Psi(E_{\gamma}, R, i = 1, \dots, I) + \sum_{i=1}^{i=I+1} \Delta t_i \cdot \Phi(E_{\gamma}, R, i)$$

$$where \qquad \Psi(E_{\gamma}, R, i = 1, \dots, I) = \sum_{i=1}^{i=I} \left[(I+1-i) \cdot \Delta t_i \cdot \Phi(E_{\gamma}, R, i) \right]$$
(5)

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where
$$\Psi\left(E_{\gamma}, R, i=1,...,I\right) = \sum_{i=1}^{i=I} \left[(I+1-i) \cdot \Delta t_i \cdot \Phi\left(E_{\gamma}, R, i\right) \right]$$

310
$$\Delta t_i = \Delta t = \Delta x / \overline{u}$$
 seconds

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5.2. Release terminated, propagation continues 312

Let the front of the plume has reached the position of the disc *I* just at the moment when the release 314 has terminated. Propagation continues to the disc positions I+1, I+2, ..., I+j. Fluence rate for the new 315 front cloud position at disc I+i+1 is calculated from the previous position I+i according to the 316 recurrent formula: 317

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$$\Phi\left(E_{\gamma}, R, i = j+1, \dots, I+j+1\right) = \Phi\left(E_{\gamma}, R, i = j, \dots, I+j\right) + \Phi\left(E_{\gamma}, R, I+j+1\right) - \Phi\left(E_{\gamma}, R, j+1\right)$$
(6)

Hence, the contribution from the leftmost disc of a parcel is skipped and the fluence $\Phi(E_n, \mathbf{R}, I+j+1)$ 320 induced by the new rightmost disc I+j+1 is calculated according to 2-D integration (3). Similar 321

considerations lead to the recurrent expression for the total fluence Ψ : 322

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$$\Psi(E_{\gamma}, R, i = 1, ..., I + j + 1) = \Psi(E_{\gamma}, R, i = 1, ..., I + j) + \sum_{i=j+1}^{i=I+j+1} \Delta t_i \cdot \Phi(E_{\gamma}, R, i)$$
(7)

Note: As mentioned in Chapter 2, the subsequent phases f>1 are simulated using the SGPM 325 algorithm which performs a large number of elemental shifts driven by the new weather conditions. 326 Following Figure 1, the plume segment shift $(s=1;f=1) \rightarrow (s=1;f=2)$ also proceeds generally in the 327 lateral direction. The concept of recurrent expressions cannot be applied here. We can use the 328 dispersion solution just after the shifts $f \rightarrow f+1$. The immediate values of the fluence rates related to 329 the new position of the plume in the end of the phase f+1 can be easily calculated using the proposed 330 stepwise 2-D computational scheme. Nevertheless, for the later phases the formula for semi-infinite 331 cloud is usually accepted (depending on vertical homogenisation of the concentration). The direct 332 utilisation of the 3-D integration can be taken into consideration for some individual areas having a 333 special significance. 334 335

5.3. An illustrative example of application of the recurrent formulae 336

We assume the release of radionuclide ¹³¹I with $E_{\gamma} = 0,3625$ MeV (γ -yield is taken to be 100%, linear 338 attenuation coefficient $\mu = 1.41\text{E}-02 \text{ (m}^{-1})$, linear energy absorption coefficient $\mu_a = 3.30969\text{E}-03 \text{ (m}^{-1})$ 339 (interpolated value). Mean free path values are $1/\mu = 7.12E+01$ m, $5/\mu = 3.56E+02$ m, and $10/\mu =$ 340

341 7.12 E+02 m. Time evolution of the fluencies/ fluence rates from one hour continuous activity release 342 9.0 E+14 Bq/hour of ¹³¹I (selected from Table 4) is simulated. Effective height h_{ef} of the release is 45 343 m, Pasquill categories of atmospheric stability F are examined (wind velocity at 10 m height u_{10} =1.0 344 m.s⁻¹). Short term meteorological forecast is for 20080111_18 (January 11th, 2008, 18.00 CET), and 345 the wind blows in the direction of 273 deg.



Figure 4. Time evolution of responses on sensors TST01 and ETEL17 from the beginning of release with
 continuous source strength 9.0 E+14 Bq/hour of ¹³¹I. Left: Continuous one-hour spreading . Right: Spread of
 the shorter plume of 6 min. duration.

Time evolution of the fluencies/ fluence rates for category F for sensors TST 01 and ETEL17 (roughly 400 m and 4 000 m respectively in direction of the plume propagation) is simulated in Figure 4. Long continuous release of ¹³¹I having duration 1 hour is examined by equations (4) and (5) (see left part). The right side of Figure 4 concerns the spreading of shorter plume of 6 minutes duration. Within the 6 minute interval the propagation is treated by equations (4) and (5). After that the continuous release stops and the cloud is torn away the source. The fluence rates and fluencies are then governed by equations (6) and (7).

6. Tests and comparisons of results

The proposed algorithm is tested for various release dynamics and model parameters. The method m/μ was examined for m=5 and m=10 but the differences are small (a few per cent). The calculations for m=5 are more than three times faster in comparison with m=10. Verification of the numerical integration algorithm expressed in equations (3) is accomplished in Appendix A. The numerical results are compared with the analytical solution of equation (3) for a special case without absorption ($\mu=0$) and build-up factor B=1 (a simplified experiment - "irradiation in vacuum"). Convergence to the semiinfinite cloud solution is examined in Section 6.3.

369 6.1. Derivation of the external irradiation dose from the photon fluencies

At first we shall formulate the relationship between the photon fluency/fluency rate and the individual effective dose/dose rate of external irradiation from the cloud. The irradiation dose rate at the receptor R is denoted by $H(E_{\gamma}, R, i = 1, ..., I)$ (Gy.s⁻¹). It represents the irradiation from monoenergetic photons

with energy E_{γ} emitted from the whole plume (with the disc *I* in the front). It can be calculated from the fluence rates (see equations (4) or (6)) according to:

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$$H(E_{\gamma}, R, i = 1, ..., I) = \frac{\omega \cdot K \cdot \mu_a \cdot E_{\gamma}}{\rho} \cdot \Phi(E_{\gamma}, R, i = 1, ..., I)$$
(8)

Conversion factor $K = 1.6 E10^{-13} Gy.kg.Mev^{-1}$; $\omega = 1.11$ is a ratio of the absorbed dose in tissue to the absorbed dose in air (more precise energy dependence is mentioned in Table 3), and the air density $\rho = 1.293 \text{ kg.m}^{-3}$. The other quantities for the release of radionuclide ¹³¹I were described in the beginning of Section 5.3. Equation (8) stands for absorbed doses expressed in grays. Common practice in the radiation protection field is to multiply the absorbed doses by relative biological effectiveness

factor F_q which accounts for different biological damage with regards to different types of ionizing 383 radiation. The corresponding radiological quantity is expressed in Sv (sieverts), where $F_q = 1$ for 384 photons. Therefore, we shall express doses in the following text and graphs in units of Sv. 385

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Figure 5. Time evolution of the effective individual cloudshine doses at positions of sensors TST01 and TST02 (400 m and 4 000 m respectively in the direction of the plume propagation). Continuous 1-hour release of 41 Ar with strength 3.33E+11 Bq.s⁻¹ (left). Short 6-minute continuous release of ¹³³Xe with strength 2.78E+14 Bq.s⁻¹ (right).

The application stemming from of equation (8) is given in Figure 5. The influence of the changing 393 meteorological conditions for Pasquill stability categories F and D (u_{10} =1.0 m.s⁻¹ and 3.0 m.s⁻¹ 394 respectively) is examined for two nuclides with different gamma energy levels. ⁴¹Ar has high photon 395 energy and long mean free path, while ¹³³Xe has low photon energy and shorter mean free path (see 396 Table 3). The source strengths of both nuclides correspond to the values in Table 4. The dispersion 397 formulae KFK-Jülich for rough terrain are used. 398

6.2. Confrontation of the cloudshine doses generated nearby the source

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Computer simulations are critical especially in high-consequence systems that can hardly ever be 402 tested in a fully representative environment. Plausibility of simulations can be tested also on consensus 403 of the computational simulations with the physical nature of the problem. An example of such partial 404 test is in Figure 6. Expected progress of both curves is confirmed. The proposed algorithm covers 405 realistically the ring of teledosimetric sensors located about 500 meters around the source. 406



407

408 Figure 6. Comparison of the finite cloud dose rates H_{finite}(z=0) calculated according to the proposed model using equation (8) with the semi-infinite approach H_{semi-inf} (z=0). E_{γ} = 1.2936 MeV for radionuclide ⁴¹Ar (γ -yield 409 is 99.1%). 410

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In the following text we shall carry out the convention comparison benchmark based on confrontation 412 of the results with several well-established international environmental codes. In the article (Bedwell 413 et al., 2010) a hypothetical scenario of ⁸⁵Kr discharge with intensity 1.0×10¹⁰ Bq.s⁻¹ over a 24 hour 414 period is analysed. Other characteristics were used: release height of 10 m, constant wind direction 415 with a speed of 5 m s⁻¹, a boundary layer depth of 800 m, heat flux of 0 W m⁻², representative Pasquill 416 stability category D, no rain, and terrain roughness of 0.3 m. Three receptor points are considered at 1, 417 2, and 5 km along the plume centre line. The effective cloud gamma dose rates are to be estimated, 418 averaged over 24 hours after the start of release. Monoenergetic photons having energy of 0.5300 419 MeV with yield $4.340 \ 10^{-3}$ per decay are assumed according to (RadDecay, 1996). We have taken 420 Table 1 from (Bedwell et al., 2010) related to the three significant European computer codes NAME 421 III (Lagrangian particle-puff trajectory model), ADMS 4 (3-D integration for calculation of photon 422 fluence, dispersion described by the new generation of Gaussian plume model based on advanced 423 parameterisation of the boundary layer structure) and PC CREAM (Gaussian quadrature for 3-D 424 numerical integration, dispersion using standard Gaussian plume model based on classical single 425 parameter Pasquill-Gifford stability categories). The original comparison from (Bedwell et al., 2010) 426 427 was extended by our results (see Table 2). The outputs were generated by the environmental code HARP (HARP, 2011) to which the new proposed algorithm for cloudshine doses estimation is fully 428 429 integrated.

430

431 **Table 2.** Model comparison for effective cloudshine dose rates for adults $(mSv.s^{-1})$ at 3 sensors along the plume 432 centre line.

	NAME III ^a	ADMS ^a	PC CREAM ^a	HARP		
				Hosker (av. 24 hours)	Hosker (no averaging)	KFK
1 km downwind	2.3 10 ⁻⁰⁹	2.1 10 ⁻⁰⁹	3.2 10 ⁻⁰⁹	2.52 10 ⁻⁰⁹	8.51 10 ⁻⁰⁹	3.44 10 ⁻⁰⁹
2 km downwind	1.1 10 ⁻⁰⁹	8.2 10 ⁻¹⁰	1.3 10 ⁻⁰⁹	1.04 10 ⁻⁰⁹	4.07 10 ⁻⁰⁹	$1.47 \ 10^{-09}$
5 km downwind	5.1 10 ⁻¹⁰	2.2 10 ⁻¹⁰	3.5 10 ⁻¹⁰	3.17 10 ⁻¹⁰	1.35 10 ⁻⁰⁹	3.79 10 ⁻¹⁰

433 ^a the values selected from (Bedwell *et al.*, 2010)

434

The HARP system is designed for sensitivity analysis and assessment of the "worst case" accidental 435 scenarios. User-friendly environment enables quick examination of variability for the input model 436 parameters. Three alternative formulae for horizontal dispersion $\sigma_{\rm v}$ are used to obtain the results 437 shown in Table 2. Hosker dispersion formulae are derived for smooth terrain using a sampling time of 438 10 minutes. Rough averaging of σ_v over a period of 24 hours was done using the recommendations 439 given in (Hanna, 1982) in order to fulfil the comparison requirements given above. For illustration, 440 results for $\sigma_{\rm v}$ related to the original sampling time of 10 minutes are also given in Table 2. The values 441 have evident physical meaning as instantaneous (un-averaged) dose rates. The results for KFK-Jülich 442 dispersion model presented in the last column in Table 2 can illustrate the sensitivity of the results 443 using the option of the alternative dispersion formulae for smooth versus rough terrain (KFK formulae 444 445 are predetermined for rough terrain of the Central European type). The results in Table 2 generated by the HARP system in near distances from the source of pollution are well comparable with the 446 established international codes. 447

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6.3. Verifying the convergence of the external γ -exposure to the semi-infinite cloud solution

The dose conversion factor (DCF) for external exposure of a person submerged in the semi-infinite

452 cloud with uniform specific radioactivity of 1 Bq.m⁻³ represents a dose rate in units ($Sv.s^{-1}.Bq^{-1}.m^3$).

The recommended factors are selected from (ICRP 74, 1996). The proposed algorithm was adjusted

454 for these special calculations. The value of radioactivity concentration C in equation (3) in ambient air

455 was assumed to be 1 Bq.m⁻³ everywhere in any disc from the plume segmentation according to Figure 456 2. Three radionuclides with markedly different average photon energies were considered according to 457 Table 3. Segment thickness Δx is 10 m (see. equation (3)), Berger's formula for build-up factor is used 458 and the integration limit is $5/\mu$ (see Figure 2). Here ω is the ratio of effective dose to air dose for the 459 respective energy for isotropic irradiation geometry (ICRP 74,1996).

We can hardly expect an excellent agreement of our computations with a detailed DCF determination 460 based on Monte Carlo calculations with a human phantom model. Photon transport mechanisms are 461 462 simplified using empirical formulae (build-up factors, ratio ω). However, Table 3 shows good agreement of the proposed algorithm with ICRP recommendations. At the same time, the results are 463 well comparable with findings of other authors, e.g. (Wang et al., 2004) where 3-D integration is 464 substituted by a three-dimensional columned space subdivision on many finite grid cells, or (Armand 465 et al., 2005) where a gamma exposure rate is simulated with 3-D Lagrangian particle model SPRAY 466 with the post-processor tool CLOUD SHINE. 467

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Table 3. Comparison of calculated dose rates with tabulated DCFs.							
Nuclide	\overline{E}^{n} (MeV)	$\omega(\overline{E}^n)$	5/µ (m)	Dose rate $(Sv.s^{-1}/(Bq/m^3))$	DCF (ICRP 74,1996) (Sv.s ⁻¹ /(Bq/m ³))		
⁴¹ Ar	1.293	0.735	6.84E+02	5.47E-14 5.93E-14 ^a	6.50E-14		
131 I	3.625E-01	0.666	3.56E+02	1.18E-14 1.545E-14 ^{a,b}	1.78E-14		
¹³³ Xe	5.230E-02	0.541	2.01E+02	1.62E-15	1.56E-15		

470 ^a Higher integration limit up to $10/\mu$; ^b Linear formula for build-up factor 471

The results shown in Table 3 are assumed to provide sophisticated particular evidence of proper functionality of the proposed technique.

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7. Accounting for multiple nuclide group

477 We assume the multiple photons p emitted with different energies E_p^n from radionuclide n which have 478 noticeable yields f_p^n (e.g. greater than 0.001). Following equation (8) the general expression for dose 479 rate ($Sv.s^{-1}$) from the multiple nuclides/multiple photons case can be rewritten as:

480
$$H(R, i=1,...,I) = \sum_{(n)} H^n(R, i=1,...,I) = \frac{\omega \cdot K}{\rho} \sum_{(n)} \sum_{(p)} \mu_a(E_p^n) \cdot f_p^n \cdot E_p^n \cdot \Phi(E_p^n, R, i=1,...,I)$$
(9)

481 The corresponding dose in *Sv* can be calculated when substituting the fluence rate Φ by the entire 482 photon fluence Ψ expressed by equation (5) or (7).

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485

484 *7.1. Averaging photon energies for each nuclide*

Reduction of the computational load can be achieved by averaging the photon energies for thenuclide *n* according to:

488
$$\overline{E}^{n} = \sum_{(p)} f_{p}^{n} \cdot E_{p}^{n} / F^{n}; \qquad F^{n} = \sum_{(p)} f_{p}^{n}$$
(10)

489 The subsequent simplified formulation for the dose rate is:

490
$$H(R, i = 1, ..., I) = \sum_{(n)} H^n(R, i = 1, ..., I) = \frac{\omega \cdot K}{\rho} \sum_{(n)} \mu_a(\overline{E}^n) \cdot \overline{E}^n \cdot F^n \cdot \Phi(\overline{E}^n, R, i = 1, ..., I)$$
(11)

491 We have examined a hypothetical release of nuclide mixture illustrated in Table 4. Dependency of

492 physical coefficients on photon energy (for linear and mass attenuation coefficients, constants in build 493 up factor formulae, etc.) is interpolated from discrete values prepared in (Pechova, 2012).

Table 4.	Hypothe	etical sour	rce term a	ind avera	ged photo	on energie	es accordi	ng to equ	ation (10).
radionuclide	⁴¹ Ar	⁸⁸ Kr	¹³¹ I	132 I	¹³⁵ I	¹³² Te	¹³³ Xe	¹³⁵ Xe	¹³⁴ Cs	¹³⁷ Cs
activity release	1.2E+	1.2E+	9.0E+	2.2E+	2.2E+	5.5E+	8.2E+	6.6E+	3.2E+	7.9E+
(Bq/hour)	15	17	14	15	15	13	17	17	13	13
\overline{E}^n - eq. (10) in MeV	1.293	1.348	0.362	0.762	1.192	0.136	0.052	0.250	0.695	0.614
half-time of decay	1.8 h	2.8 h	8.01 d	2.3 h	6.6 h	78.6 h	5.2 d	9.1 h	2.06 y	30.0 y

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The outputs presented here are results of the model simulations using the proposed technique just at the points of existing fixed monitoring networks. The bilinear interpolation technique is used for determination of the values in an arbitrary location.



Figure 7. Response of sensor TST01 in the photon fluence rate (left) and dose rate (right) on a short release of 6-minutes duration. Sensor TST01 is located at a distance of about 400 m from the source, roughly in the direction of the plume propagation. Multi-nuclide source term is defined according to Table 4.

Part of the results generated according to the simplified scheme (11) for sensor TST 01 is 505 demonstrated for each nuclide in Figure 7. The radionuclide mixture is discharged into the atmosphere 506 with a category stability class F. The effective height of release is h^{ef} =45 meters, and wind speed at a 507 height of 10 m is $u_{10} = 1.0$ m.s⁻¹. Due to dependency of H in equation (11) on energy, the shape of 508 curves for photon fluence rates (left) somewhat differs from the corresponding dose rates (right). The 509 calculations for all nuclides and for all sensors are running in one stroke. A significant outcome is 510 achieved by computation effectiveness, when the complete run for all nuclides and all sensors lasts 511 about 90 seconds on a PC with a standard, common configuration. 512

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514 7.2. Substitution of multi-nuclide approach to multi-group scheme

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Equation (3) is formulated for simplified case of a nuclide emitting one photon with average energy E_{γ}

517 per decay. Some nuclides have a rather wide spectrum of emitted photons. We can expect a certain

inaccuracy to be introduced to the results when using computational schemes (10) and (11) with only

average energy. The straightforward solution offers a detailed scheme given by equation (9). But it

- could cause a huge escalation of computational load and the main goal of a real time analysis may not
- 521 be achievable.

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- 522 An alternative method is proposed here with the goal of making further calculations more accurate and
- at the same time sufficiently fast for a large group of nuclides discharged into the atmosphere. The whole range of possible photon energy levels is partitioned into *G* energetic groups: G=24 and
- alternatively *G*=8 were selected according to (Pechova, 2012; RadDecay, 1996). Probability and
- emitted energy values were extracted for each photon p of a cascade belonging to each nuclide from
- 527 the nuclide mixture. Linear total gamma attenuation coefficients μ and linear gamma energy-
- absorption coefficients μ_a are interpolated on the basis of the same energetic separation. Let ${}^{n}E_{p}^{s}$ stands
- for energy of each photon p emitted by the nuclide n having energy belonging to the group g with the
- 530 yield of ${}^{n}f_{p}^{g}$. The mean energy $\overline{E}^{g}(x_{I})$ averaged over all photons emitted to the energy interval g
- from all radionuclides n at downwind distance x_I can be found using the "source depletion" approach
- 532 introduced in equation (1): $A^n(x_l, y=0, z=h_{ef}) = A^n(x=0, y=0, z=h_{ef}) \cdot f^n_R(x_l) \cdot f^n_W(x_l)$. The
- values of $\overline{E}^{g}(x_{I})$ are determined according to equation (12). Depletion factors for dry and wet deposition $f^{n}_{F}(x_{I})$ and $f^{n}_{W}(x_{I})$ have to be distinguished according to the physical-chemical forms of radionuclides, land use characteristics of the terrain and precipitation intensity - more details can be found in the documentation of the HARP product (HARP, 2011).
- 537

538
$$\overline{E}^{g}(x_{I}) = \sum_{n=1}^{N} A^{n}(x_{I}) \cdot \overline{E}_{n}^{g} \cdot F_{n}^{g} / \sum_{n=1}^{N} A^{n}(x_{I}) F_{n}^{g}; \quad \overline{E}_{n}^{g} = \sum_{(p(n))} {}^{n}E_{p}^{g} \cdot {}^{n}f_{p}^{g}; \quad F_{n}^{g} = \sum_{(p(n))} {}^{n}f_{p}^{g}$$
(12)

539

The denominator in equation (12) represents the total number of photons emitted in disc *I* per second from all nuclides belonging to the group *g*. Now we introduce an expression for the photon fluence rate from the total number of photons emitted from all nuclides belonging to the energetic group *g*. After separation of the nuclide part and the spatial integration part, equation (3) can be rewritten as:

544
$$\Phi^{g}\left(\overline{E}^{g}(x_{I}), R, I\right) = SUM\left(x_{I}; g\right) \cdot INTEG\left(x_{I}; R, g\right)$$
(13)

545

$$SUM(x_{I};g) = \sum_{(n)} A^{n} \cdot f_{R}^{\ n}(x_{I}) \cdot f_{F}^{\ n}(x_{I}) \cdot f_{W}^{\ n}(x_{I}) \frac{1}{24} \frac{1}{6} \frac{1}{6} \frac{547}{547}$$

$$548 \qquad INTEG(x_{I};R,g) = \frac{\Delta x}{4\pi} \int_{r=0}^{r \max} \int_{\varphi=0}^{2\pi} \frac{DISPER(x_{I};y,z) \cdot B(\overline{E}^{\ g}(x_{I}),\mu(\overline{E}^{\ g}(x_{I})) \cdot d) \cdot \exp(-\mu(\overline{E}^{\ g}(x_{I})) \cdot d)}{d^{2}} r \, d\varphi \, dr$$

Г

549
$$DISPER(x_I; y = y(r, \varphi), z = z(r, \varphi)) = \frac{1}{2\pi \cdot \sigma_y(x_I) \cdot \sigma_z(x_I) \cdot \overline{u}} \exp(-\frac{y^2}{2\sigma_y^2(x_I)}) \exp(-\frac{(z - h_{ef})^2}{2\sigma_z^2(x_I)}) +$$

551

+ exp $\left(-\frac{(z+h_{ef})^{2}}{2\sigma_{z}^{2}(x_{I})}\right)$ + exp $\left(-\frac{(z-2H_{mix}+h_{ef})^{2}}{2\sigma_{z}^{2}(x_{I})}\right)$ + $\eta_{JV}(z)$

552 Where INTEG is expressed in analogy with equation (1), but specifically stands for distribution of the 553 fluence rate of photons at receptor point R from all nuclides contributing to the energetic group g. The 554 resulting values are given by summing over all energetic groups g. It substitutes the former procedure 555 based on the cycle over all nuclides.

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557 7.3. Performance of multi-group approximation

The main achievement of the outlined technique illustrated above is the fact, that the time consuming integration INTEG is nuclide independent. Earlier repetitive estimation for each nuclide (or in detail for each photon *p* emitted by a nuclide described by equation (9)) can be avoided. This alternative scheme is assumed to accelerate calculations for the scenarios with a large number (several tens) of discharged nuclides. For a medium group of 10 nuclides from Table 4, the former calculations according to expression (11) (run1) are compared with the multi-group approach for a fine resolution

into 24 energetic groups (run2) and a rough resolution into 8 groups (run3). The computation of run3 565 is about three times faster than run2 and about 2.5 times faster than run1. The substantial advantage 566 will be brought for large nuclide groups. The computational time of run1 is expected to be linearly 567 proportional to the nuclide count while the computational time of the multi-group approach will be 568 more or less constant, regardless of the increasing count of nuclides. As for dose estimates, for the 569 medium nuclide group from Table 4, a small mutual differences have occurred. More systematic 570 examination should be carried out for scenarios with a large number of released nuclides. Grouping of 571 the gamma rays according to energies was extended (Pechova, 2012) for additional nuclides belonging 572 to an extensive release of a hypothetical radiation accident. A hypothetical severe accident with the 573 574 training source term ST2 selected from the RODOS system has been now recalculated using the proposed multigroup scheme. The scenario is initiated by LOCA accident (Loss of Cooling Accident) 575 in combination with the subsequent events described in (Pechova, 2003). A large group of discharged 576 radionuclides is taken into account (37 in total). The conclusion related to the performance of the 577 multigroup scheme was verified. 578

579

580 8. Discussion and conclusions

581

582 A fast algorithm is presented for estimation of external irradiation from radioactive cloud nearby the source of pollution. The proposed unconventional finite cloud approach avoids the severe 583 underestimation of cloudshine doses nearby the source arising from utilisation of the formerly used 584 semi-infinite plume model. Thanks to its fast and effective operation this solution supports potency of 585 the advanced consequence assessment techniques for improvement of emergency preparedness and 586 management. The proposed method provides simulation of time and space evolution of cloudshine 587 doses in the early phase of an accident in a real-time mode and on a detailed timescale. Large mixtures 588 of discharged nuclides can be effectively treated simultaneously when the usual multi-nuclide 589 approach is substituted by the new multi-group scheme. This software tool is incorporated into the 590 routine operation of the environmental code HARP (HARP, 2011) with the aim for it to serve as a 591 proper component supporting the advanced data assimilation techniques to be computationally feasible 592 (Pecha et al., 2009; ASIM, 2012; Hofman et al., 2013). An experience with the particle filter 593 sampling approximation was gained there for the solution of this complex task, which is analytically 594 intractable. 595

Large uncertainties involved in an accident scenario and information noise occurring in the beginning of a calamity constitute a cardinal problem for the decision making staff. For example the uncertainty

in the source term dominates among all other uncertainties of an accidental release scenario.

599 Estimated radiological values can differ from the true ones by a factor of 10 or more. An improvement

of the dose predictions in the specific nearest vicinity of the source of pollution taking into account the

601 teledosimetric ring of sensors on fence of the nuclear power facility plays a decisive role in the source 602 term re-estimation and inverse modelling. Such extraction of information from observations for the

602 term re-estimation and inverse modelling. Such extraction of information from observations for the 603 model parameter improvement increases credibility of the consequence assessment. The predictions of

the potentially affected areas and the corresponding contamination levels can be recursively

605 reconstructed.

606 Practically all advanced assimilation methods perform computationally expensive multiple repetitive 607 recall of the environmental model. Hence the formulation of a fast and effective routine for

determination of the external irradiation doses is of a crucial significance. It has to comply with other

609 specific requirements in order to cover a large net of measuring apparatus located on the terrain which

should include both fixed stations and various sensors on potential mobile vehicles. Furthermore, the

⁶¹¹ routine is capable of managing the problem of a large mixture of discharging radionuclides when a

new multi-group approach is introduced.

This article addresses here only the cloudshine dose calculations. However, the measuring devices

detect cloudshine and groundshine doses in total. For assimilation purposes a simplified assessment of

615 contribution from the activity deposited on the ground (based on tabulated conversion factors) to the

external irradiation has been applied (Pecha et al., 2009, Smidl et al., 2013). In this conservative case

an individual is assumed to be standing on a smooth infinite plane with a uniform source

618 concentration. More detailed examinations should be related to additive modifying factors taking into

- account the effects of ground roughness and non-uniform source distribution. For these particular 619
- cases an effect of a possible near-standing shielding object should be taken into consideration. 620
- Finally, it should be pointed out that the originated plume segmentation method based on the stepwise 621
- 2-D computational approach presented here can be considered a certain fast dispersion scheme 622 alternative to the puff model.
- 623 624

Appendix A. Verification of the proposed algorithm for numerical integration 625

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The photon fluence rate given by expression (3) is integrated numerically using the Gauss-Legendre 627 integration formula which is the most commonly used form of Gaussian quadratures. The Gaussian 628 quadratures provide the flexibility of choosing not only the weighting coefficients but also the 629 locations (abscissas) where the function values are evaluated. The Gauss-Legendre formula is based 630 on the Legendre polynomials of the first kind $P_m(x)$. For the chosen degree m of the polynomial we 631 have tested the limits of its applicability on a given experimental configuration illustrated in Figure 8. 632 An emitting disc with optional the radius r_{max} is located in the plane (y,z) with its centre in the origin of 633 the coordinate system. We assume that without restriction to generality we can simplify the 634 expression (3) in three manners: 635

- Uniform radioactivity concentration on the disc surface is assumed ($C(x; r, \varphi) = 1 Bq/m^2$) 636 0
- No photon absorption takes place in the medium between the disc and the receptor point R 637 0 638 $(\mu = 0)$
- The photons are emitted from the disc elements isotropically and without any secondary 639 0 640
 - collision on their path from the source up to the receptor point (the build-up factor is 1)



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643

Figure 8. Disc in plane (y,z) irradiating the receptor *R*.

With exaggeration, it can be perceived as a "vacuum experiment" for the disc and receptors located 644 in the outer space. Photon fluence rate $(m^{-2} s^{-1})$ is now expressed by simplified equation (3): 645

646
$$\Phi(E_{\gamma}, R) = \frac{1}{4\pi} \int_{r=0}^{r_{\text{max}}} \int_{\varphi=0}^{2\pi} \frac{1}{d^2} r \, d\varphi \, dr$$
(14)

According to Figure 8 the distance d between the sensor R and elemental surface $r d\phi dr$ equals to 647

648
$$d = d(r,\varphi) = \sqrt{a^2 + b^2 + r^2 - 2 \cdot r \cdot a \cdot \cos \varphi}$$

Equation (14) can be integrated analytically and the number of photons crossing 1 m^2 per second at the 649 position of the sensor R is expressed as: 650

651
$$\Phi(E_{\gamma}, R) = \frac{1}{4} \ln \left(\frac{r_{\max}^{2} + b^{2} - a^{2} + sqrt\left(r_{\max}^{4} + 2r_{\max}^{2}(b^{2} - a^{2}) + \left(a^{2} + b^{2}\right)^{2}\right)}{2b^{2}} \right)$$
(15)

A 30-point Gauss-Legendre integration formula is used to numerically integrate equation (14) for various ranges of constants *a* and *b*. A partial comparison of numerical and analytical values is presented in Table A1. Additional tests revealed a certain numerical instability for a case when the sensor *R* lies in the plane of the disc (*b*=0) and constant *a* is approaching zero. In this instance we are using the lowest value of constant *b* slightly above zero ($b \approx 0.2$ m).

657 658

Table A1. Comparison of numerical and analytical values of photon fluence rate for various values *a*, *b* of sensor R positions. Radius of the radiating disc is r_{max} =49 m.

659 660

		Photon fluence rate $\Phi(m^{-2}s^{-1})$			
a (m)	b (m)	analytically – see (15)	numerically – see (14)		
144	144	1.446555 E-02	1.446555 E-02		
60	60	8.189546 E-02	8.189548 E-02		
10	10	7.950500 E-01	7.950501 E-01		
1.0	1.0	1.945767 E+00	1.945910 E+00		
0.5	0.5	2.290156 E+00	2.292484 E+00		
0.2	0.2	2.744151 E+00	2.750629 E+00		
0.1	0.1	3.064821 E+00	3.097203 E+00		

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